

Amendments to the Specification

Please replace paragraph [0030] with the following amended paragraph:

Referring to Fig. 6, a simplified block diagram of a method embodied by the present invention is shown. Initially, before operation, a camera is positioned to view a properly aligned conveyor, 61. Next, a digital pixel representation of conveyor alignment is generated 62, as described herein. A coordinate system is then set for zero alignment, 63. The coordinate system, in one embodiment, is superimposed on a video monitor showing the image of the conveyor. Each increment on the coordinate system, left or right of zero error, represents a certain number of pixels according to the width of a pixel. During operation, the actual pixel representation of alignment is compared to the zero error 64, using a computer or manually on the video monitor 15. Steps 62 and 64 are repeated according to scan interval 65. When a threshold of misalignment is reached 66, according to a certain number of pixels of misalignment, a signal is sent to the motor 43 to correct the misalignment 68. If the misalignment is less than the threshold, then no alignment correction is needed 67. Also, as shown by items 66A, 67A, 66B, AND 66B, alarm and shut down trip points, according to selectable magnitudes of misalignments can be incorporated into the method.